

Half-Positional Objectives Recognized by Deterministic Büchi Automata

Patricia Bouyer¹, Antonio Casares²,
Mickael Randour³, **Pierre Vandenhove**^{1,3}

¹Université Paris-Saclay, CNRS, ENS Paris-Saclay, LMF, France

²LaBRI, Université de Bordeaux, France

³F.R.S.-FNRS & UMONS – Université de Mons, Belgium

June 29, 2022 – Highlights of Logic, Games and Automata

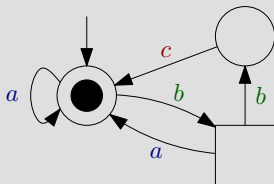


Laboratoire
Méthodes
Formelles



Games on graphs

Zero-sum turn-based games on graphs

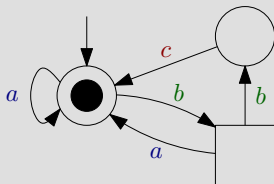


Games on graphs

Zero-sum turn-based games on graphs

P_1 : ○

P_2 : □

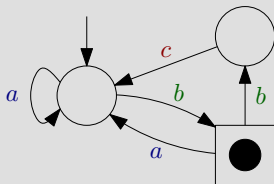


Games on graphs

Zero-sum turn-based games on graphs

P_1 : ○

P_2 : □



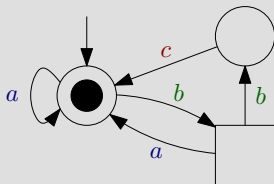
$w = b$

Games on graphs

Zero-sum turn-based games on graphs

P_1 : ○

P_2 : □



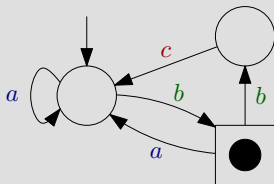
$$w = ba$$

Games on graphs

Zero-sum turn-based games on graphs

P_1 : ○

P_2 : □



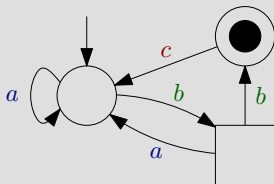
$w = bab$

Games on graphs

Zero-sum turn-based games on graphs

P_1 : ○

P_2 : □



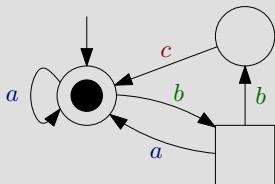
$w = babb$

Games on graphs

Zero-sum turn-based games on graphs

P_1 : ○

P_2 : □



$w = b a b b c \dots$

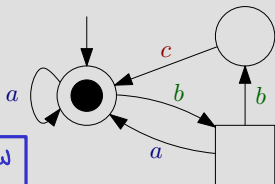
Games on graphs

Zero-sum turn-based games on graphs

P_1 : ○

P_2 : □

Objectives: $W \leq C^w$



$w = b a b b c \dots$

$C = \{a, b, c\}$

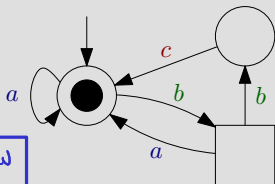
Games on graphs

Zero-sum turn-based games on graphs

P_1 : ○

P_2 : □

Objectives: $W \subseteq C^w$



$w = babbbc\dots$

$C = \{a, b, c\}$

Motivation

Understand the **objectives** for which **simple** strategies suffice to win.

Half-positionality

Strategies

A **strategy** of \mathcal{P}_1 is a function $\sigma: E^* \rightarrow E$.

It is **positional** if the choices only depend on the **current** vertex.

Half-positionality

Strategies

A **strategy** of \mathcal{P}_1 is a function $\sigma: E^* \rightarrow E$.

It is **positional** if the choices only depend on the **current** vertex.

Half-positional objectives

In all games, if \mathcal{P}_1 can win for objective W with a strategy $\sigma: E^* \rightarrow E$, can \mathcal{P}_1 also win with a **positional** strategy?

Half-positionality

Strategies

A **strategy** of \mathcal{P}_1 is a function $\sigma: E^* \rightarrow E$.

It is **positional** if the choices only depend on the **current** vertex.

Half-positional objectives

In all games, if \mathcal{P}_1 can win for objective W with a strategy $\sigma: E^* \rightarrow E$, can \mathcal{P}_1 also win with a **positional** strategy?

Existing results

- **Sufficient** conditions for half-positionality.^{1,2}
- Structural **characterization!**³

¹Kopczyński, “Half-Positional Determinacy of Infinite Games”, 2006.

²Bianco et al., “Exploring the boundary of half-positionality”, 2011.

³Ohlmann, “Characterizing Positionality in Games of Infinite Duration over Infinite Graphs”, 2022.

Objectives

Common class of objectives finitely representable:
 ω -regular objectives.

Objectives

Common class of objectives finitely representable:
 ω -regular objectives.

Open problem

Half-positionality **not** completely understood for ω -regular objectives!

Objectives

Common class of objectives finitely representable:
 ω -regular objectives.

Open problem

Half-positionality **not** completely understood for ω -regular objectives!

Here

Effective characterization of **half-positional** objectives recognized by **deterministic Büchi automata** (DBA).

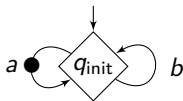
DBA recognize a **subclass** of the ω -regular objectives.

Examples

 "Büchi transitions"

$C = \{a, b\}$.

- $W = \text{Büchi}(a) =$ "seeing a infinitely often": half-positional.⁴



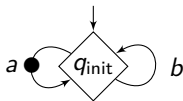
⁴Emerson and Jutla, "Tree Automata, Mu-Calculus and Determinacy (Extended Abstract)", 1991.

Examples

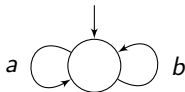
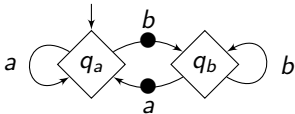
 "Büchi transitions"

$C = \{a, b\}$.

- $W = \text{Büchi}(a) =$ "seeing a infinitely often": half-positional.⁴



- $W = \text{Büchi}(a) \cap \text{Büchi}(b)$: **not** half-positional.



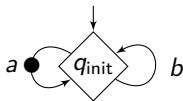
⁴Emerson and Jutla, "Tree Automata, Mu-Calculus and Determinacy (Extended Abstract)", 1991.

Examples

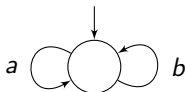
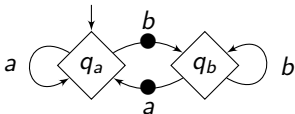
 "Büchi transitions"

$C = \{a, b\}$.

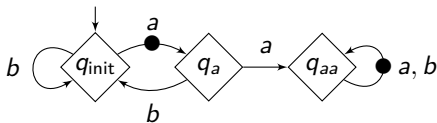
- $W = \text{Büchi}(a) =$ "seeing a infinitely often": half-positional.⁴



- $W = \text{Büchi}(a) \cap \text{Büchi}(b)$: **not** half-positional.



- $W = \text{Büchi}(a) \cup C^*aaC^\omega$: half-positional.



⁴Emerson and Jutla, "Tree Automata, Mu-Calculus and Determinacy (Extended Abstract)", 1991.

Characterization

Let W be recognized by a DBA \mathcal{B} .

Main result

Characterization of half-positionality of W with a conjunction of **three** conditions.

Characterization

Let W be recognized by a DBA \mathcal{B} .

Main result

Characterization of half-positionality of W with a conjunction of **three** conditions. *~> No time to explain all of them :-)*

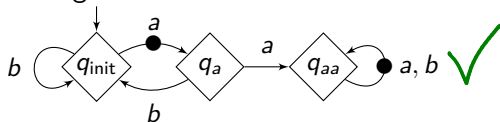
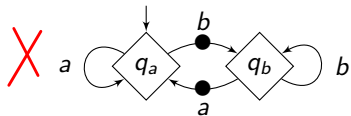
Characterization

Let W be recognized by a DBA \mathcal{B} .

Main result

Characterization of half-positionality of W with a conjunction of **three** conditions.

Intuition for **one** condition: what distinguishes these two DBA?



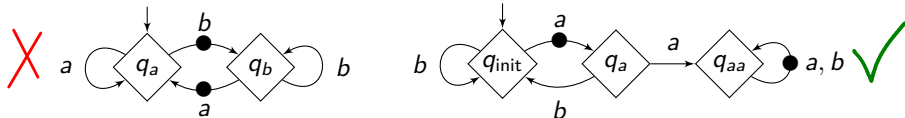
Characterization

Let W be recognized by a DBA \mathcal{B} .

Main result

Characterization of half-positionality of W with a conjunction of **three** conditions.

Intuition for **one** condition: what distinguishes these two DBA?



- Left: needs two states for the objective, but “equivalent” (same objective when taken as initial states).

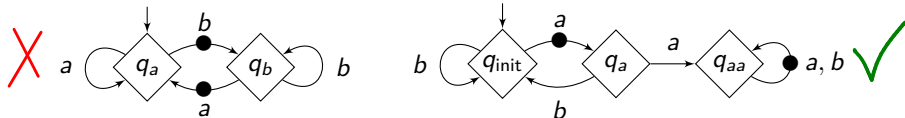
Characterization

Let W be recognized by a DBA \mathcal{B} .

Main result

Characterization of half-positionality of W with a conjunction of **three** conditions.

Intuition for **one** condition: what distinguishes these two DBA?



- Left: needs two states for the objective, but “equivalent” (same objective when taken as initial states).
- Right: three states, all recognizing different objectives.

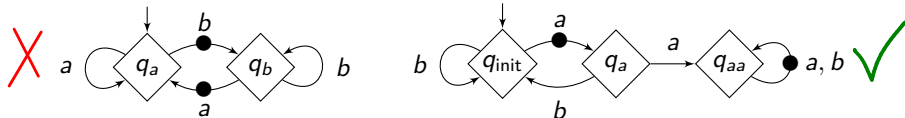
Characterization

Let W be recognized by a DBA \mathcal{B} .

Main result

Characterization of half-positionality of W with a conjunction of **three** conditions.

Intuition for **one** condition: what distinguishes these two DBA?



- Left: needs two states for the objective, but “equivalent” (same objective when taken as initial states).
- **Right: three states, all recognizing different objectives.**

Being “**Myhill-Nerode**-like” is necessary for half-positionality.

Conclusion: two corollaries

Let W be recognized by a DBA \mathcal{B} .

Polynomial-time algorithm

Half-positionality of W can be **decided** in $\mathcal{O}(|\mathcal{B}|^4)$ time.

Conclusion: two corollaries

Let W be recognized by a DBA \mathcal{B} .

Polynomial-time algorithm

Half-positionality of W can be **decided** in $\mathcal{O}(|\mathcal{B}|^4)$ time.

One-to-two-player, finite-to-infinite lift

If W is half-positional over **finite one-player** graphs, then also in **infinite two-player** games!

Conclusion: two corollaries

Let W be recognized by a DBA \mathcal{B} .

Polynomial-time algorithm

Half-positionality of W can be **decided** in $\mathcal{O}(|\mathcal{B}|^4)$ time.

One-to-two-player, finite-to-infinite lift

If W is half-positional over **finite one-player** graphs, then also in **infinite two-player** games!

Thanks!

Conclusion: two corollaries

Let W be recognized by a DBA \mathcal{B} .

Polynomial-time algorithm

Half-positionality of W can be **decided** in $\mathcal{O}(|\mathcal{B}|^4)$ time.

One-to-two-player, finite-to-infinite lift

If W is half-positional over **finite one-player** graphs, then also in **infinite two-player** games!

Thanks!

Appendix

Relations on prefixes

Let $W \subseteq C^\omega$ be an objective.

Left quotient

For $u \in C^*$, $u^{-1}W = \{w \in C^\omega \mid uw \in W\}$.

For $u, v \in C^*$,

- $u \sim v$ if $u^{-1}W = v^{-1}W$ (\approx Myhill-Nerode relation),
- $u \preceq v$ if $u^{-1}W \subseteq v^{-1}W$.

Condition 1: \preceq is total

Let $W \subseteq C^\omega$ be an objective.

Condition 1

Prefix preorder \preceq is total.

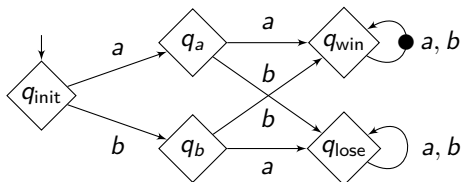
Condition 1: \preceq is total

Let $W \subseteq C^\omega$ be an objective.

Condition 1

Prefix preorder \preceq is total.

For $W = (aa + bb)C^\omega$, words a and b are not comparable for \preceq .



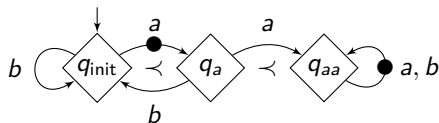
Condition 1: \preceq is total

Let $W \subseteq C^\omega$ be an objective.

Condition 1

Prefix preorder \preceq is total.

Büchi(a) $\cup C^*aaC^\omega$ has a total prefix preorder.



Condition 2: progress-consistency

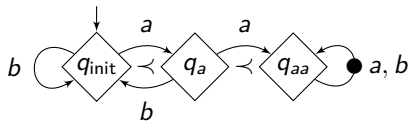
Let $W \subseteq C^\omega$ be an objective.

Condition 2

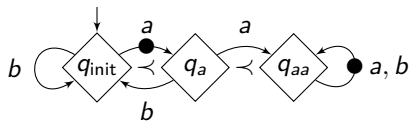
Objective W is **progress-consistent** if

for all $u, v \in C^*$, $u \prec uv$ implies $uv^\omega \in W$.

C^*aaC^ω is **not** progress-consistent:
 $b \prec b(ba)$ but $b(ba)^\omega \notin W$.



$\text{Büchi}(a) \cup C^*aaC^\omega$ is progress-consistent (here, $b(ba)^\omega \in W$).



Condition 3: one state per class

Let $W \subseteq C^\omega$ be an objective recognized by a DBA.

Condition 3

Objective W is **Myhill-Nerode-like** if it is recognized by a DBA with one state per equivalence class for \sim .

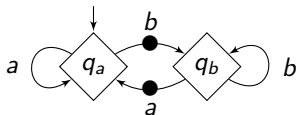
Condition 3: one state per class

Let $W \subseteq C^\omega$ be an objective recognized by a DBA.

Condition 3

Objective W is **Myhill-Nerode-like** if it is recognized by a DBA with one state per equivalence class for \sim .

$\text{Büchi}(a) \cap \text{Büchi}(b)$ is **not** Myhill-Nerode-like. **One** equivalence class, but needs at least **two** states.



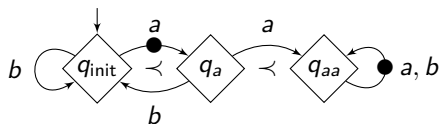
Condition 3: one state per class

Let $W \subseteq C^\omega$ be an objective recognized by a DBA.

Condition 3

Objective W is **Myhill-Nerode-like** if it is recognized by a DBA with one state per equivalence class for \sim .

$\text{Büchi}(a) \cup C^*aaC^\omega$ is Myhill-Nerode-like (**three** classes, **three** states).



Characterization

Theorem

An objective W recognized by a DBA is half-positional **if and only if**

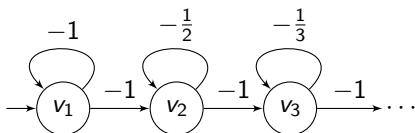
- \preceq_W is total,
- W is progress-consistent, and
- W is Myhill-Nerode-like.

All three conditions are easy to decide.

Greater memory requirements in **infinite** arenas in general

Objective: get a mean payoff ≥ 0 .

- Memoryless strategies suffice in finite (even stochastic) arenas.
- Infinite memory is required in one-player deterministic infinite arenas.⁵



\rightsquigarrow Possible to get 0 at the limit **with infinite memory**.

⁵Puterman, *Markov Decision Processes: Discrete Stochastic Dynamic Programming*, 1994.