

Games Where You Can Play Optimally with Arena-Independent Finite Memory

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Outline

Strategy synthesis for two-player turn-based games

Design **optimal** controllers for systems interacting with an **antagonistic** environment.

“Optimal” w.r.t. an objective or a specification.

Goal: interest in “simple” controllers

Finite-memory determinacy: when do **finite-memory** controllers suffice?

Inspiration

Results by Gimbert and Zielonka¹ about **memoryless** determinacy.

¹Gimbert and Zielonka, “Games Where You Can Play Optimally Without Any Memory”, 2005.

1 Memoryless determinacy

2 The need for memory

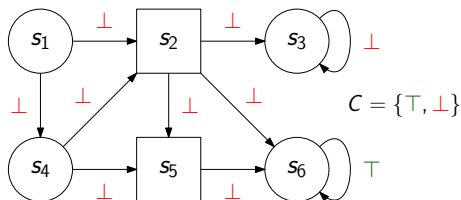
3 Arena-independent finite memory

1 Memoryless determinacy

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Two-player turn-based zero-sum games on graphs



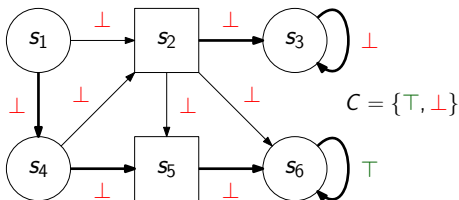
- **Finite** two-player arenas: S_1 (circles, for \mathcal{P}_1) and S_2 (squares, for \mathcal{P}_2), edges E .
- Set C of **colors**. **Edges** are colored.
- “Objectives” given by **preference relations** $\sqsubseteq \in C^\omega \times C^\omega$ (total preorder). **Zero-sum**, \sqsubseteq^{-1} .
- A strategy for \mathcal{P}_i is a (partial) function $\sigma: E^* \rightarrow E$.

Memoryless determinacy

Question

Given a preference relation, do “simple” strategies suffice to play optimally in all arenas?

A strategy σ of \mathcal{P}_i is *memoryless* if it is a function ~~E^*~~ $S_i \rightarrow E$.



E.g., for reachability, *memoryless* strategies suffice.

Also suffice for safety, Büchi, co-Büchi, parity, mean-payoff, energy, average-energy...

Memoryless determinacy

Good understanding of memoryless determinacy:

- **sufficient** conditions to guarantee memoryless optimal strategies for **both** players.^{2,3}
- **sufficient** conditions to guarantee memoryless optimal strategies for **one** player.^{4,5,6}
- **characterization** of the preference relations admitting optimal memoryless strategies for **both** players.⁷

²Gimbert and Zielonka, "When Can You Play Positionally?", 2004.

³Aminof and Rubinfeld, "First-cycle games", 2017.

⁴Kopczynski, "Half-Positional Determinacy of Infinite Games", 2006.

⁵Gimbert, "Pure Stationary Optimal Strategies in Markov Decision Processes", 2007.

⁶Gimbert and Kelmendi, "Two-Player Perfect-Information Shift-Invariant Submixing Stochastic Games Are Half-Positional", 2014.

⁷Gimbert and Zielonka, "Games Where You Can Play Optimally Without Any Memory", 2005.

Gimbert and Zielonka's characterization⁸

Let \sqsubseteq be a preference relation. Two results:

- 1 Characterization of memoryless determinacy w.r.t. properties of \sqsubseteq .
- 2 Corollary:

One-to-two-player memoryless lifting

If

- ▶ in all **one-player** arenas of \mathcal{P}_1 , \mathcal{P}_1 has an optimal memoryless strategy,
- ▶ in all **one-player** arenas of \mathcal{P}_2 , \mathcal{P}_2 has an optimal memoryless strategy,

then both players have an optimal memoryless strategy in all **two-player** arenas.

Extremely useful in practice. Very easy to recover memoryless determinacy of, e.g., mean-payoff and parity games.

⁸Gimbert and Zielonka, "Games Where You Can Play Optimally Without Any Memory", 2005.

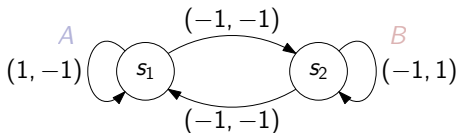
1 Memoryless determinacy

2 The need for memory

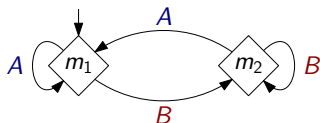
3 Arena-independent finite memory

The need for memory

Memoryless strategies do not always suffice.



- Büchi(A) \wedge Büchi(B): requires **finite memory**.



- Mean payoff ≥ 0 in both dimensions: requires **infinite memory**.⁹

\rightsquigarrow **Combinations of objectives** usually require memory.

⁹Chatterjee, Doyen, et al., "Generalized Mean-payoff and Energy Games", 2010.

An attempt at lifting [GZ05] to FM determinacy

- Lack of a good understanding of finite-memory determinacy.
- **Related work:** sufficient properties to preserve FM determinacy in **Boolean combinations of objectives**.¹⁰
- Our approach:

Hope: extend Gimbert and Zielonka's results

One-to-two-player lifting for ~~memoryless~~ **finite-memory** determinacy.

¹⁰Le Roux, Pauly, and Randour, "Extending Finite-Memory Determinacy by Boolean Combination of Winning Conditions", 2018.

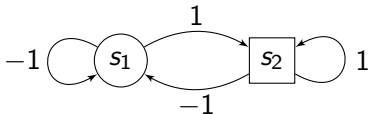
Counterexample

Let $C \subseteq \mathbb{Z}$. \mathcal{P}_1 wants to achieve a play $\pi = c_1 c_2 \dots \in C^\omega$ s.t.

$$\limsup_n \sum_{i=0}^n c_i = +\infty \quad \text{or} \quad \exists^\infty n, \sum_{i=0}^n c_i = 0.$$

Optimal **FM** strategies in **one-player** arenas...

... but not in **two-player** arenas: \mathcal{P}_1 wins but needs **infinite memory**.



Intuition:

In one-player arenas, \mathcal{P}_1 can bound the memory he needs in advance.

In two-player arenas, \mathcal{P}_2 can generate arbitrarily long sequences.

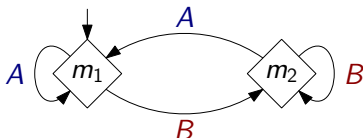
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Arena-independent memory

- For $\text{Büchi}(A) \wedge \text{Büchi}(B)$, this structure suffices to play optimally on **all** arenas for \mathcal{P}_1 .



- The counterexample fails because in one-player arenas, the size of the memory is **dependent on the size of the arena**.
- Observation: for many objectives, one **fixed memory structure** suffices **for all arenas**.

“For all \mathcal{A} , does there exist $\mathcal{M} \dots$?”

→ “**Does there exist \mathcal{M} , for all $\mathcal{A} \dots$?**”

Method: reproducing the approach of Gimbert and Zielonka **given a memory structure \mathcal{M}** .

Characterization of arena-independent determinacy

Let \sqsubseteq be preference relation, \mathcal{M} be a memory structure.

- 1 Characterization of “playing with \mathcal{M} is sufficient” in terms of properties of \sqsubseteq .
- 2 Corollary:

One-to-two-player lifting

If

- ▶ in all **one-player** arenas of \mathcal{P}_1 , \mathcal{P}_1 has an optimal strategy with memory \mathcal{M}_1 ,
- ▶ in all **one-player** arenas of \mathcal{P}_2 , \mathcal{P}_2 has an optimal strategy with memory \mathcal{M}_2 ,

then both players have an optimal strategy in all **two-player** arenas with memory $\mathcal{M}_1 \otimes \mathcal{M}_2$.

In short: the study of **one-player arenas** is sufficient to determine whether playing with **arena-independent finite memory** suffices.

Applicability and limits

- **Applies to** objectives with optimal **arena-independent** strategies:
 - ▶ generalized reachability,¹¹
 - ▶ generalized parity,¹²
 - ▶ window parity,¹³
 - ▶ lower- and upper-bounded (multi-dimensional) energy games.^{14, 15}
- **Does not apply to**, e.g., multi-dimension lower-bounded energy objectives:¹⁶ the size of the finite memory depends on the arena.

¹¹Fijalkow and Horn, “The surprising complexity of reachability games”, 2010.

¹²Chatterjee, Henzinger, and Piterman, “Generalized Parity Games”, 2007.

¹³Bruyère, Hautem, and Randour, “Window parity games: an alternative approach toward parity games with time bounds”, 2016.

¹⁴Bouyer, Markey, et al., “Average-energy games”, 2018.

¹⁵Bouyer, Hofman, et al., “Bounding Average-Energy Games”, 2017.

¹⁶Chatterjee, Randour, and Raskin, “Strategy synthesis for multi-dimensional quantitative objectives”, 2014.

Conclusion

Key observation: many objectives require **arena-independent** memory.

Contributions

- Characterization of **arena-independent** finite-memory determinacy.
- **One-to-two-player lifting**.
- Generalization of Gimbert and Zielonka's work.

Future work

Understand (arena-**dependent**) finite-memory determinacy through the study of one-player arenas.

Thanks!