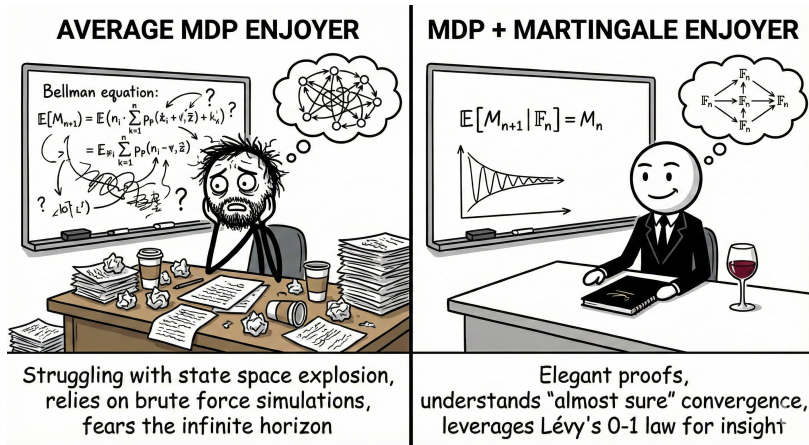


Martingale Theory for the Average MDP Enjoyer

Pierre Vandenhove

December 1, 2025 — UMONS Formal Methods Reading Group

Martingale theory for the average MDP enjoyer



- Left: me in 2019.
- Right: me in 2020, after discovering martingales.

Sample Problem

Let $\mathcal{M} = (S, s_0, P)$ be an (**infinite**) Markov chain and $\top \in S$.

For some $p > 0$, define the set of states from which \top is reached with probability at least p :

$$\text{Reach}_{\geq p} = \{s \in S \mid \mathbb{P}_s(\Diamond \top) \geq p\}.$$

Sample Problem

Let $\mathcal{M} = (S, s_0, P)$ be an (**infinite**) Markov chain and $\top \in S$.

For some $p > 0$, define the set of states from which \top is reached with probability at least p :

$$\text{Reach}_{\geq p} = \{s \in S \mid \mathbb{P}_s(\Diamond \top) \geq p\}.$$

Theorem

If you visit $\text{Reach}_{\geq p}$ infinitely often, then you reach \top almost surely, i.e.,

$$\mathbb{P}_{s_0}(\Diamond \top \mid \Box \Diamond \text{Reach}_{\geq p}) = 1.$$

Sample Problem

Let $\mathcal{M} = (S, s_0, P)$ be an (**infinite**) Markov chain and $\top \in S$.

For some $p > 0$, define the set of states from which \top is reached with probability at least p :

$$\text{Reach}_{\geq p} = \{s \in S \mid \mathbb{P}_s(\Diamond \top) \geq p\}.$$

Theorem

If you visit $\text{Reach}_{\geq p}$ infinitely often, then you reach \top almost surely, i.e.,

$$\mathbb{P}_{s_0}(\Diamond \top \mid \Box \Diamond \text{Reach}_{\geq p}) = 1.$$

Intuitively true.

Sample Problem

Let $\mathcal{M} = (S, s_0, P)$ be an (**infinite**) Markov chain and $\top \in S$.

For some $p > 0$, define the set of states from which \top is reached with probability at least p :

$$\text{Reach}_{\geq p} = \{s \in S \mid \mathbb{P}_s(\Diamond \top) \geq p\}.$$

Theorem

If you visit $\text{Reach}_{\geq p}$ infinitely often, then you reach \top almost surely, i.e.,

$$\mathbb{P}_{s_0}(\Diamond \top \mid \Box \Diamond \text{Reach}_{\geq p}) = 1.$$

Intuitively true.

→ Perhaps your intuition follows the second **Borel-Cantelli lemma**: if events have summed probability $+\infty$, they happen infinitely often.

Sample Problem

Let $\mathcal{M} = (S, s_0, P)$ be an (**infinite**) Markov chain and $\top \in S$.

For some $p > 0$, define the set of states from which \top is reached with probability at least p :

$$\text{Reach}_{\geq p} = \{s \in S \mid \mathbb{P}_s(\Diamond \top) \geq p\}.$$

Theorem

If you visit $\text{Reach}_{\geq p}$ infinitely often, then you reach \top almost surely, i.e.,

$$\mathbb{P}_{s_0}(\Diamond \top \mid \Box \Diamond \text{Reach}_{\geq p}) = 1.$$

Intuitively true.

→ Perhaps your intuition follows the second **Borel-Cantelli lemma**: if **independent** events have summed probability $+\infty$, they happen infinitely often.

Why it is not trivial

Here, the events “ $\diamond T$ from various states” are **not independent!**

Perhaps it behaves like this counter-example:

- Let X_i be the outcome of a die roll (same die, rolled once).
- Let A be the event “Obtaining 6”.
- We define $A_1 = A_2 = \dots = A$ (perfect dependence).

The sum of probabilities is infinite, but probability of “eventually” occurring is $\frac{1}{6} \neq 1$.

Why it is not trivial

Here, the events “ $\diamond T$ from various states” are **not independent!**

Perhaps it behaves like this counter-example:

- Let X_i be the outcome of a die roll (same die, rolled once).
- Let A be the event “Obtaining 6”.
- We define $A_1 = A_2 = \dots = A$ (perfect dependence).

The sum of probabilities is infinite, but probability of “eventually” occurring is $\frac{1}{6} \neq 1$.

How to prove it, then? MARTINGALE THEORY

Before martingales

In 2019, unaware of martingales, we wrote an explicit proof for (a version of) this problem.

1.6. Theorem




Figure 1.7. State i is not eventually visited almost surely from state i .

Let us first build a formula ϕ :

$$\phi = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_0) = \frac{1}{2} \left(\text{Pr}(\text{Reach}(i) \mid \mathcal{F}_1) + \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_2) \right)$$

Let $i \in V$. Clearly, there is only one path leading to i for the first time in state i in a path from i to itself. Let us denote this path by P_i .

$$P_i = \{i, i_1, i_2, \dots, i_k, i\}$$

By using that $\text{Pr}(P_i \mid \mathcal{F}_0) = \text{Pr}(P_i \mid \mathcal{F}_1) = \dots = \text{Pr}(P_i \mid \mathcal{F}_k)$, we find that since before visiting i we are not at i :

$$\phi = \frac{1}{2} \left(\text{Pr}(P_i \mid \mathcal{F}_1) + \text{Pr}(P_i \mid \mathcal{F}_2) \right) = \frac{1}{2} \left(\text{Pr}(P_i \mid \mathcal{F}_1) + \text{Pr}(P_i \mid \mathcal{F}_2) \right)$$

Since the martingale has state i , the probability to eventually reach i is 1. In other words, we have $\phi = 1$. For each $i \in V$, we have $\phi = 1$. So we have:

$$\text{Pr}(\text{Reach}(i) \mid \mathcal{F}_0) = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_1) = \dots = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_k) = 1$$

1.6. Theorem

Suppose that the only way to win is by visiting a particular probability to happen. If we had not had to go to state i to win, then ϕ_i would have been zero.

$$\text{Pr}(\text{Reach}(i) \mid \mathcal{F}_0) = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_1) = \dots = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_k) = 1$$

The difference with the previous proof is that in this example, the state i is not eventually visited almost surely from state i . Instead, it is visited almost surely from state i . So we have:

$$\text{Pr}(\text{Reach}(i) \mid \mathcal{F}_0) = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_1) = \dots = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_k) = 1$$

Let us now consider the case where i is not eventually visited almost surely from state i . In this case, we have:

$$\text{Pr}(\text{Reach}(i) \mid \mathcal{F}_0) = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_1) = \dots = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_k) = 0$$

Let us now consider the case where i is not eventually visited almost surely from state i . In this case, we have:

$$\text{Pr}(\text{Reach}(i) \mid \mathcal{F}_0) = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_1) = \dots = \text{Pr}(\text{Reach}(i) \mid \mathcal{F}_k) = 0$$

1.6. Theorem

The solution can be written as $\phi_i = \frac{1}{2} \left(\phi_{i_1} + \phi_{i_2} \right)$.

$$\phi_i = \frac{1}{2} \left(\phi_{i_1} + \phi_{i_2} \right)$$

We have a particular case:

$$\phi_i = \frac{1}{2} \left(\phi_{i_1} + \phi_{i_2} \right)$$

We assume that the conditional distribution μ_{i_1} is well defined if none of these states is visited. This means that the probability of the corresponding states μ_{i_1} is zero, which is not the case after the following lemma. In that lemma, we have the assumption:

$$\mu_{i_1} = \mu_{i_2} = \dots = \mu_{i_k} = 0$$

Let us now consider the following case: if i is not eventually visited almost surely from state i :

$$\phi_i = \frac{1}{2} \left(\phi_{i_1} + \phi_{i_2} \right)$$

The idea is that we want to show that ϕ_i is equal to zero. We have seen that ϕ_i is equal to zero if i is not eventually visited almost surely from state i . So we have:

$$\phi_i = \frac{1}{2} \left(\phi_{i_1} + \phi_{i_2} \right)$$

Let us now consider the case where i is not eventually visited almost surely from state i . In this case, we have:

$$\phi_i = \frac{1}{2} \left(\phi_{i_1} + \phi_{i_2} \right)$$

Let us now consider the case where i is not eventually visited almost surely from state i . In this case, we have:

$$\phi_i = \frac{1}{2} \left(\phi_{i_1} + \phi_{i_2} \right)$$



After martingales

In 2020, we received a comment from a reviewer “*I think this is a trivial application of martingale theory*”...

After martingales

In 2020, we received a comment from a reviewer “*I think this is a trivial application of martingale theory*”... AND IT WAS!

Proof. In order not to obfuscate the interesting ideas of the proof with technical considerations, we first prove the lemma for $n = 0$ (with $\mathcal{A} = \mathcal{A} \in \Sigma$), and explain afterwards how to extend the proof to obtain the general statement. We want to prove that for all $\mu \in \text{Dist}(S)$,

$$\text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A}) = 0.$$

Let $\mu \in \text{Dist}(S)$ be an initial distribution. We assume w.l.o.g. that $A \cap B = \emptyset$ —indeed, if that is not the case, we simply notice that $\text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A}) = \text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A} \cap B^c)$ and we replace \mathcal{A} by $\mathcal{A} \cap B^c$ in the rest of the proof.

Let us consider a modified STS \mathcal{T}_B which is equal to T , except that B is made absorbing (we assume that for $s \in B$, $\kappa(s, \cdot)$ is the Dirac distribution δ_s). Notice that $\text{Prob}_\mu^T(\mathbf{F} B) = \text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{F} B)$, and $\text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A}) \leq \text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{G} \mathcal{A})$ (as $A \cap B = \emptyset$, runs that see A infinitely often without seeing B in T are just as likely in \mathcal{T}_B). Notice also that the event $\mathbf{F} B$ is shift-invariant. We have

$$\begin{aligned} \text{Ev}_{\mathcal{T}_B}(\mathbf{G} \mathcal{A}) &= \{\rho = s_0 s_1 \dots \in S^\omega \mid \forall i, \exists j \geq i, s_j \in A\} \\ &\subseteq \{\rho = s_0 s_1 \dots \in S^\omega \mid \forall i, \exists j \geq i, \text{Prob}_{s_j}^{\mathcal{T}_B}(\mathbf{F} B) \geq p\} && \text{by hypothesis on } A \\ &= \{\rho = s_0 s_1 \dots \in S^\omega \mid \forall i, \exists j \geq i, \text{Prob}_{s_j}^{\mathcal{T}_B}(\mathbf{F} B) \geq p\} && \text{by construction of } \mathcal{T}_B \\ &= \{\rho \in S^\omega \mid \forall i, \exists j \geq i, E_\mu^{\mathcal{T}_B}(\mathbf{1}_{\mathbf{F} B} \mid \mathcal{F}_{j+1})(\rho) \geq p\} && \text{by Lemma 17, as } \mathbf{F} B \text{ is shift-invariant} \\ &\subseteq \{\rho \in S^\omega \mid \lim_{i \rightarrow \infty} E_\mu^{\mathcal{T}_B}(\mathbf{1}_{\mathbf{F} B} \mid \mathcal{F}_i)(\rho) \text{ is not } 0 \text{ if it exists}\} \\ &= \{\rho \in S^\omega \mid \mathbf{1}_{\mathbf{F} B}(\rho) \neq 0\} && \text{by Lévy's zero-one law (Proposition 16)} \\ &= \{\rho \in S^\omega \mid \mathbf{1}_{\mathbf{F} B}(\rho) = 1\} \\ &= \text{Ev}_{\mathcal{T}_B}(\mathbf{F} B). \end{aligned}$$

All inclusions and equalities are almost sure. In \mathcal{T}_B , as $A \cap B = \emptyset$ and B is absorbing, we have that $\text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{G} \mathcal{A} \wedge \mathbf{F} B) = 0$. As $\text{Ev}_{\mathcal{T}_B}(\mathbf{G} \mathcal{A}) \subseteq \text{Ev}_{\mathcal{T}_B}(\mathbf{F} B)$, this implies that $\text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{G} \mathcal{A}) = 0$. We conclude

$$\text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A}) \leq \text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{G} \mathcal{A}) = 0.$$



After martingales

In 2020, we received a comment from a reviewer “*I think this is a trivial application of martingale theory*”... AND IT WAS!

Proof. In order not to obfuscate the interesting ideas of the proof with technical considerations, we first prove the lemma for $n = 0$ (with $\mathcal{A} = \mathcal{A} \in \Sigma$), and explain afterwards how to extend the proof to obtain the general statement. We want to prove that for all $\mu \in \text{Dist}(S)$,

$$\text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A}) = 0.$$

Let $\mu \in \text{Dist}(S)$ be an initial distribution. We assume w.l.o.g. that $A \cap B = \emptyset$ —indeed, if that is not the case, we simply notice that $\text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A}) = \text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A} \cap B^c)$ and we replace \mathcal{A} by $\mathcal{A} \cap B^c$ in the rest of the proof.

Let us consider a modified STS \mathcal{T}_B which is equal to \mathcal{T} , except that B is made absorbing (we assume that for $s \in B$, $\kappa(s, \cdot)$ is the Dirac distribution δ_s). Notice that $\text{Prob}_\mu^T(\mathbf{F} B) = \text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{F} B)$, and $\text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A}) \leq \text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{G} \mathcal{A})$ (as $A \cap B = \emptyset$, runs that see A infinitely often without seeing B in \mathcal{T} are just as likely in \mathcal{T}_B). Notice also that the event $\mathbf{F} B$ is shift-invariant. We have

$$\text{Ev}_{\mathcal{T}_B}(\mathbf{G} \mathcal{A})$$

$$= \{\rho = s_0 s_1 \dots \in S^\omega \mid \forall i, \exists j \geq i, s_j \in A\}$$

$$\subseteq \{\rho = s_0 s_1 \dots \in S^\omega \mid \forall i, \exists j \geq i, \text{Prob}_{s_j}^{\mathcal{T}_B}(\mathbf{F} B) \geq p\}$$

by hypothesis on A

$$= \{\rho = s_0 s_1 \dots \in S^\omega \mid \forall i, \exists j \geq i, \text{Prob}_{s_j}^{\mathcal{T}_B}(\mathbf{F} B) \geq p\}$$

by construction of \mathcal{T}_B

$$= \{\rho \in S^\omega \mid \forall i, \exists j \geq i, E_\mu^{\mathcal{T}_B}[\mathbf{1}_{\mathbf{F} B} \mid \mathcal{F}_{j+1}](\rho) \geq p\}$$

by Lemma 17, as $\mathbf{F} B$ is shift-invariant

$$\subseteq \{\rho \in S^\omega \mid \lim_{i \rightarrow \infty} E_\mu^{\mathcal{T}_B}[\mathbf{1}_{\mathbf{F} B} \mid \mathcal{F}_i](\rho) \text{ is not 0 if it exists}\}$$

$$= \{\rho \in S^\omega \mid \mathbf{1}_{\mathbf{F} B}(\rho) \neq 0\}$$

by Lévy's zero-one law (Proposition 16)

$$= \{\rho \in S^\omega \mid \mathbf{1}_{\mathbf{F} B}(\rho) = 1\}$$

$$= \text{Ev}_{\mathcal{T}_B}(\mathbf{F} B).$$

All inclusions and equalities are almost sure. In \mathcal{T}_B , as $A \cap B = \emptyset$ and B is absorbing, we have that $\text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{G} \mathcal{A} \wedge \mathbf{F} B) = 0$. As $\text{Ev}_{\mathcal{T}_B}(\mathbf{G} \mathcal{A}) \subseteq \text{Ev}_{\mathcal{T}_B}(\mathbf{F} B)$, this implies that $\text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{G} \mathcal{A}) = 0$. We conclude

$$\text{Prob}_\mu^T(\mathbf{G} B^c \wedge \mathbf{G} \mathcal{A}) \leq \text{Prob}_\mu^{\mathcal{T}_B}(\mathbf{G} \mathcal{A}) = 0.$$



Rest of the talk: **Definition of martingales, key theorems, and two applications to verification.**

Conditional Expectation

Conditional Expectation w.r.t. a σ -algebra (1/2)

Let $(\Omega, \mathcal{B}, \mathbb{P})$ be a probability space, $X: \Omega \rightarrow \mathbb{R}$ a random variable, and $\mathcal{F} \subseteq \mathcal{B}$ a sub- σ -algebra.

- The definition of martingales requires the notion of **conditional expectation w.r.t. a σ -algebra** (not just w.r.t. an event). It is a **function** $\mathbb{E}[X \mid \mathcal{F}]: \Omega \rightarrow \mathbb{R}$.
- **Hard definition:** Non-constructive in the general continuous case, requires a hard proof (*Radon–Nikodym theorem*) just to show it exists and is unique.

Conditional Expectation w.r.t. a σ -algebra (1/2)

Let $(\Omega, \mathcal{B}, \mathbb{P})$ be a probability space, $X: \Omega \rightarrow \mathbb{R}$ a random variable, and $\mathcal{F} \subseteq \mathcal{B}$ a sub- σ -algebra.

- The definition of martingales requires the notion of **conditional expectation w.r.t. a σ -algebra** (not just w.r.t. an event). It is a **function** $\mathbb{E}[X \mid \mathcal{F}]: \Omega \rightarrow \mathbb{R}$.
- **Hard definition:** Non-constructive in the general continuous case, requires a hard proof (*Radon–Nikodym theorem*) just to show it exists and is unique.
- Easier argument (according to Matthieu): see it as a projection in L^2 space.
 - Still hard for the average computer scientist/MDP enjoyer.

Conditional Expectation w.r.t. a σ -algebra (2/2)

- In our case, we mainly need the definition **for a finite σ -algebra \mathcal{F}** (and thus generated by a finite partition into “atoms” $\{B_i\}$). Easy definition: for $\omega \in \Omega$,

$$\mathbb{E}[X \mid \mathcal{F}](\omega) = \frac{1}{\mathbb{P}(B)} \int_B X \, d\mathbb{P}$$

where B is the unique element of the partition such that $\omega \in B$.

Conditional Expectation w.r.t. a σ -algebra (2/2)

- In our case, we mainly need the definition **for a finite σ -algebra \mathcal{F}** (and thus generated by a finite partition into “atoms” $\{B_i\}$). Easy definition: for $\omega \in \Omega$,

$$\mathbb{E}[X \mid \mathcal{F}](\omega) = \frac{1}{\mathbb{P}(B)} \int_B X \, d\mathbb{P}$$

where B is the unique element of the partition such that $\omega \in B$.

Important reminder: $\mathbb{E}[X \mid \mathcal{F}]$ is a **random variable** $\Omega \rightarrow \mathbb{R}$, not a real number!

Conditional Expectation w.r.t. a σ -algebra (2/2)

- In our case, we mainly need the definition **for a finite σ -algebra \mathcal{F}** (and thus generated by a finite partition into “atoms” $\{B_i\}$). Easy definition: for $\omega \in \Omega$,

$$\mathbb{E}[X \mid \mathcal{F}](\omega) = \frac{1}{\mathbb{P}(B)} \int_B X \, d\mathbb{P}$$

where B is the unique element of the partition such that $\omega \in B$.

Important reminder: $\mathbb{E}[X \mid \mathcal{F}]$ is a **random variable** $\Omega \rightarrow \mathbb{R}$, not a real number!

Information-theoretic intuition

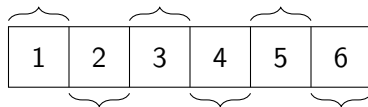
$\mathbb{E}[X \mid \mathcal{F}]$ is the most that we can know about X given information that we can glean from observing \mathcal{F} . It is finer than just $\mathbb{E}[X]$ (no information), but coarser than X (full information).

Example: The Die

- $\Omega = \{1, \dots, 6\}$
- $X(\omega) = \omega$ (The value)
- $P = \text{fair die}$
- $\mathcal{F} = \{\emptyset, \{1, 3, 5\}, \{2, 4, 6\}, \Omega\}$
(Information: odd or even)

$$\mathbb{E}[X \mid \mathcal{F}](\omega) = \begin{cases} \frac{1+3+5}{3} = \mathbf{3} & \text{if } \omega \in \{1, 3, 5\} \\ \frac{2+4+6}{3} = \mathbf{4} & \text{if } \omega \in \{2, 4, 6\} \end{cases}$$

Odd \rightarrow Expectation 3



Even \rightarrow Expectation 4

Properties of the conditional expectation

- 1 If X is \mathcal{F} -measurable (i.e., observing \mathcal{F} gives you everything there is to know about X):

$$\mathbb{E}[X \mid \mathcal{F}] = X.$$

- 2 If $\mathcal{F} = \{\emptyset, \Omega\}$ (no information at all):

$$\mathbb{E}[X \mid \mathcal{F}] = \frac{1}{\mathbb{P}(\Omega)} \int_{\Omega} X \, d\mathbb{P} = \int_{\Omega} X \, d\mathbb{P} = \mathbb{E}[X] \quad (\text{constant}).$$

- 3 If $\mathcal{F}_1 \subseteq \mathcal{F}_2$:

$$\mathbb{E}[\mathbb{E}[X \mid \mathcal{F}_2] \mid \mathcal{F}_1] = \mathbb{E}[X \mid \mathcal{F}_1].$$

Projecting a projection returns the coarser projection.

Markov Chain Example (1/2)

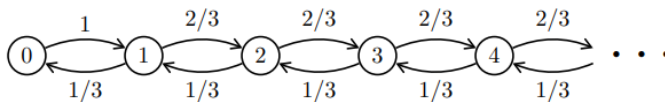
Let $\mathcal{M} = (S, P)$ be a Markov chain (possibly infinite).

- $\Omega = S^\omega$ (infinite paths).
- We define a family of σ -algebras: for $n \in \mathbb{N}$, let

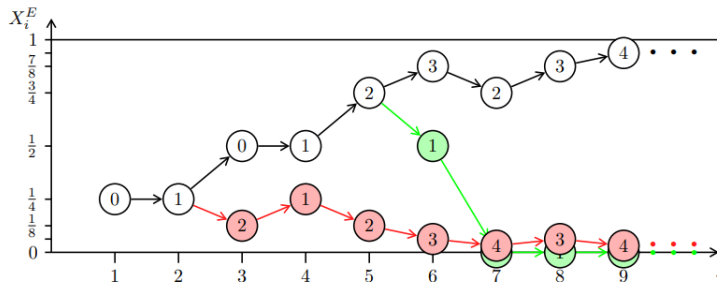
$$\begin{aligned}\mathcal{F}_n &= \text{“exactly the information about the first } n \text{ steps”} \\ &= \sigma \left(\bigcup_{h \in S^n} \text{Cyl}(h) \right).\end{aligned}$$

Markov Chain Example (2/2)¹

Consider this infinite Markov chain:



Let E be the event “exactly two visits to state 0”. Consider the values $X_i^E(\rho) = \mathbb{E}[\mathbb{1}_E \mid \mathcal{F}_i](\rho)$ for a few runs ρ .



¹From Kiefer, Mayr, Shirmohammadi, Totzke, Wojtczak: *How to Play in Infinite MDPs*. ICALP'20.

Martingales

Definitions

- A (discrete-time) **stochastic process** is a sequence $(X_n)_{n \in \mathbb{N}}$ of random variables.
- A **filtration** is an infinite sequence $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{B}$ of σ -algebras.
- $(X_n)_n$ is **adapted** to $(\mathcal{F}_n)_n$ if for all n , X_n is \mathcal{F}_n -measurable.

Definitions

- A (discrete-time) **stochastic process** is a sequence $(X_n)_{n \in \mathbb{N}}$ of random variables.
- A **filtration** is an infinite sequence $\mathcal{F}_0 \subseteq \mathcal{F}_1 \subseteq \dots \subseteq \mathcal{B}$ of σ -algebras.
- $(X_n)_n$ is **adapted** to $(\mathcal{F}_n)_n$ if for all n , X_n is \mathcal{F}_n -measurable.

Definition

The sequence X_n is a **martingale** if:

$$\mathbb{E}[X_{n+1} \mid \mathcal{F}_n] = X_n.$$

Intuition: Think of a **fair sequential game** such that the average value at step $n + 1$, when you know the first n steps, is your gain after n steps.

Martingale Example: Betting

Let Y_1, Y_2, \dots be independent bets that win either $+1$ or -1 with probability $\frac{1}{2}$.

Let $X_n = Y_1 + \dots + Y_n$ (your money after n bets).

Martingale Example: Betting

Let Y_1, Y_2, \dots be independent bets that win either $+1$ or -1 with probability $\frac{1}{2}$.

Let $X_n = Y_1 + \dots + Y_n$ (your money after n bets).

Drawing: **blackboard**.

Martingale Example: Betting

Let Y_1, Y_2, \dots be independent bets that win either $+1$ or -1 with probability $\frac{1}{2}$.

Let $X_n = Y_1 + \dots + Y_n$ (your money after n bets).

Drawing: **blackboard**.

Proof that $(X_n)_n$ is a martingale:

$$\begin{aligned}\mathbb{E}[X_{n+1} \mid \mathcal{F}_n] &= \mathbb{E}[X_n + Y_{n+1} \mid \mathcal{F}_n] \\ &= \mathbb{E}[X_n \mid \mathcal{F}_n] + \mathbb{E}[Y_{n+1} \mid \mathcal{F}_n] \quad (\text{linearity of expectation}) \\ &= X_n + \mathbb{E}[Y_{n+1}] \quad (X_n \text{ is } \mathcal{F}_n\text{-measurable, } \mathcal{F}_n \text{ is independent from } Y_{n+1}) \\ &= X_n + 0 \\ &= X_n.\end{aligned}$$

The “Usual” Martingale for Markov Chains

All the uses I have seen of martingales in verification have the following form.

Take a reasonable random variable X about *infinite* runs (e.g., $X = \mathbb{1}_{\text{Büchi}(\top)}$).

Doob Martingale

Take $X_n = \mathbb{E}[X \mid \mathcal{F}_n]$.

Lemma. $(X_n)_n$ is a martingale.

The “Usual” Martingale for Markov Chains

All the uses I have seen of martingales in verification have the following form.
Take a reasonable random variable X about *infinite* runs (e.g., $X = \mathbb{1}_{\text{Büchi}(\top)}$).

Doob Martingale

Take $X_n = \mathbb{E}[X \mid \mathcal{F}_n]$.

Lemma. $(X_n)_n$ is a martingale.

Proof:

$$\begin{aligned}\mathbb{E}[X_{n+1} \mid \mathcal{F}_n] &= \mathbb{E}[\underbrace{\mathbb{E}[X \mid \mathcal{F}_{n+1}]}_{X_{n+1}} \mid \mathcal{F}_n] \\ &= \mathbb{E}[X \mid \mathcal{F}_n] \\ &= X_n.\end{aligned}$$

Theorems to Know

First Key Theorem: Doob's Convergence Theorem

Doob's Convergence Theorem

If $(X_n)_n$ is a bounded martingale, then there is a random variable X_∞ such that $X_n \rightarrow X_\infty$ almost surely.

I.e., for almost all “runs” ρ , $X_n(\rho)$ converges to $X_\infty(\rho)$ as $n \rightarrow \infty$.

Second Key Theorem: Lévy's 0-1 Law

Take the Doob martingale $X_n = \mathbb{E}[X \mid \mathcal{F}_n]$. By Doob's: $X_n \rightarrow X_\infty$ a.s.
It can be shown that $X_\infty = \mathbb{E}[X \mid \mathcal{F}_\infty]$ where $\mathcal{F}_\infty = \sigma(\bigcup_n \mathcal{F}_n)$.

Lévy's 0-1 Law

If we take $X = \mathbb{1}_A$ for an event $A \in \mathcal{F}_\infty$:

$$\mathbb{E}[\mathbb{1}_A \mid \mathcal{F}_n] \rightarrow \mathbb{E}[\mathbb{1}_A \mid \mathcal{F}_\infty] = \mathbb{1}_A.$$

Second Key Theorem: Lévy's 0-1 Law

Take the Doob martingale $X_n = \mathbb{E}[X \mid \mathcal{F}_n]$. By Doob's: $X_n \rightarrow X_\infty$ a.s.
It can be shown that $X_\infty = \mathbb{E}[X \mid \mathcal{F}_\infty]$ where $\mathcal{F}_\infty = \sigma(\bigcup_n \mathcal{F}_n)$.

Lévy's 0-1 Law

If we take $X = \mathbb{1}_A$ for an event $A \in \mathcal{F}_\infty$:

$$\mathbb{E}[\mathbb{1}_A \mid \mathcal{F}_n] \rightarrow \mathbb{E}[\mathbb{1}_A \mid \mathcal{F}_\infty] = \mathbb{1}_A.$$

Consequences for Markov Chains

- $\mathbb{P}(\{\rho \mid \lim X_n(\rho) \in \{0, 1\}\}) = 1$.
- **Almost all runs converge to 0 or 1** as you observe them!
- Moreover, $\lim X_n(\rho) = \mathbb{1}_A$: it converges to 1 if the run ρ is in A , to 0 otherwise!
- All runs “show” at the limit if they are in A or not!

Two Applications

App #1: Back to Motivating Problem

Reminder: Let $\mathcal{M} = (S, s_0, P)$ be an (infinite) Markov chain and $\top \in S$. For $p > 0$, define

$$\text{Reach}_{\geq p} = \{s \in S \mid \mathbb{P}_s(\Diamond \top) \geq p\}.$$

Theorem

$$\mathbb{P}_{s_0}(\Diamond \top \mid \Box \Diamond \text{Reach}_{\geq p}) = 1$$

App #1: Back to Motivating Problem

Reminder: Let $\mathcal{M} = (S, s_0, P)$ be an (infinite) Markov chain and $\top \in S$. For $p > 0$, define

$$\text{Reach}_{\geq p} = \{s \in S \mid \mathbb{P}_s(\Diamond \top) \geq p\}.$$

Theorem

$$\mathbb{P}_{s_0}(\Diamond \top \mid \Box \Diamond \text{Reach}_{\geq p}) = 1$$

Proof:

- 1 Let $X = \mathbb{1}_{\Diamond \top}$ and $X_n = \mathbb{E}[\mathbb{1}_{\Diamond \top} \mid \mathcal{F}_n]$.
- 2 If we visit $\text{Reach}_{\geq p}$ infinitely often, then for infinitely many n 's, $X_n(\rho) \geq p > 0$.
- 3 But $X_n(\rho) \rightarrow 0$ or 1 (by **Lévy's 0-1 Law**, using that $\Diamond \top \in \mathcal{F}_\infty$).
- 4 It does not converge to 0 (infinitely often $\geq p$).
- 5 So it converges to 1.
- 6 So runs are almost surely in $\Diamond \top$.

App #2: Hypothesis Testing: Tiger POMDP

Tiger POMDP: **blackboard**.

- Assume \mathcal{F}_n is the information after n listens (observations).
- Let X_n^L be the probability to be in L after n listens: $X_n^L = \mathbb{E}[\mathbb{1}_L \mid \mathcal{F}_n]$.
- It is a martingale, so by Doob: X_n^L converges.
- **However**, $\mathbb{1}_L$ is not \mathcal{F}_∞ -measurable (we are never completely sure about the tiger's position). So no Lévy's 0-1 Law directly. . .

Proof of Convergence

Claim: It still converges to 0 or 1 at the limit! Doob's tells us $X_n^L(\rho)$ converges a.s.

Assume $X_n^L(\rho) \rightarrow x \notin \{0, 1\}$.

Then the ratio converges to a constant:

$$\frac{X_n^L(\rho)}{X_n^R(\rho)} \rightarrow \frac{x}{1-x}.$$

But, by Bayes rule:

$$\frac{X_{n+1}^L(\rho)}{X_{n+1}^R(\rho)} = \frac{X_n^L(\rho)}{X_n^R(\rho)} \cdot \underbrace{\frac{P(o_{n+1} | L)}{P(o_{n+1} | R)}}_{\text{Observation Ratio}}.$$

If observations are *distinguishing*, this factor makes **too big of a jump** to converge to anything but 0 or $+\infty$!

So $X_n^L(\rho) \rightarrow \{0, 1\}$ a.s.: at the limit, we are almost surely sure about the tiger's position!