

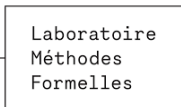
Characterizing ω -Regularity Through Finite-Memory Determinacy of Games on Infinite Graphs

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Outline

Strategy synthesis for zero-sum turn-based games

Design **optimal** controllers for systems interacting with an **antagonistic** environment.

Interest in “simple” strategies

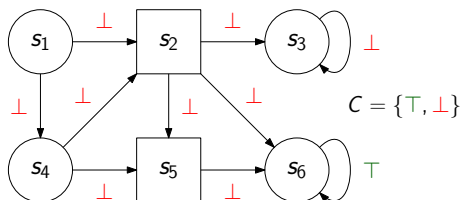
Finite-memory determinacy: when do **finite-memory** strategies suffice?
Focus on games on **infinite** graphs.

Inspiration

Results about **memoryless determinacy**.¹

¹Colcombet and Niwiński, “On the positional determinacy of edge-labeled games”, 2006.

Zero-sum turn-based games on graphs



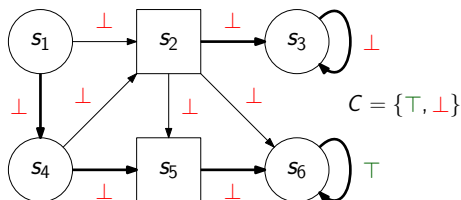
- Two-player **arenas**: S_1 (\circ , for \mathcal{P}_1) and S_2 (\square , for \mathcal{P}_2), edges E .
- Set C of **colors**. **Edges** are colored.
- **Objectives** are sets $W \subseteq C^\omega$. **Zero-sum**.
- **Strategy** for \mathcal{P}_i : function $\sigma: E^* \rightarrow E$.

Memoryless determinacy

Question

For an objective, do *simple* strategies suffice to play optimally in all arenas?

A strategy σ of \mathcal{P}_i is *memoryless* if it is a function $\mathcal{E}^* S_i \rightarrow E$.



E.g., for $\text{Reach}(T)$, **memoryless** strategies suffice to play optimally.

Also suffice for Büchi, parity... objectives.

Memoryless determinacy

Good understanding of **memoryless determinacy in finite arenas**

Sufficient conditions and **characterizations** of memoryless determinacy

- for **one** player,^{2,3,4,5}
- for **both** players.^{6,7,8}

What about **infinite** arenas?

²Kopczyński, "Half-Positional Determinacy of Infinite Games", 2006.

³Gimbert, "Pure Stationary Optimal Strategies in Markov Decision Processes", 2007.

⁴Bianco et al., "Exploring the boundary of half-positionality", 2011.

⁵Gimbert and Kelmendí, "Submixing and Shift-Invariant Stochastic Games", 2014.

⁶Gimbert and Zielonka, "When Can You Play Positionally?", 2004.

⁷Aminof and Rubin, "First-cycle games", 2017.

⁸Gimbert and Zielonka, "Games Where You Can Play Optimally Without Any Memory", 2005.

What about **infinite arenas**?

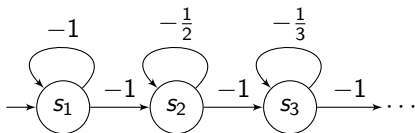
Motivations

- 1 Links between the **strategy complexity** in finite and **infinite** arenas?
- 2 Similar sufficient conditions/characterizations for **infinite** arenas?
↔ Classical proof technique for finite arenas (induction on number of edges) not suited to infinite arenas.

Greater memory requirements in **infinite** arenas

Colors $C = \mathbb{Q}$, objective $W =$ “get a *mean payoff* ≥ 0 ”.

- **Memoryless** strategies sufficient in **finite** arenas.⁹
- **Infinite** memory required in **infinite** arenas.¹⁰



\rightsquigarrow Possible to get 0 at the limit **with infinite memory**:
loop increasingly many times in states s_n .

⁹Ehrenfeucht and Mycielski, “Positional Strategies for Mean Payoff Games”, 1979.

¹⁰Puterman, *Markov Decision Processes: Discrete Stochastic Dynamic Programming*, 1994.

Nice result

Let $W \subseteq C^\omega$ be a **prefix-independent** objective.

Characterization of **memoryless** determinacy¹¹

If **memoryless strategies** suffice to play optimally for **both** players in all **infinite arenas**, then W is a **parity condition**.

Parity condition: there exists $p: C \rightarrow \{0, \dots, n\}$ such that

$$w = c_1 c_2 \dots \in W \iff \limsup_i p(c_i) \text{ is even.}$$

Characterization since **parity conditions are memoryless-determined**.¹²

¹¹Colcombet and Nawiński, “On the positional determinacy of edge-labeled games”, 2006.

¹²Zielonka, “Infinite Games on Finitely Coloured Graphs with Applications to Automata on Infinite Trees”, 1998.

Two possible extensions

- 1 What about **strategies** with **finite memory**?
↪ More and more prevalent in the literature.
- 2 Some simple memoryless-determined objectives are not **prefix-independent** (e.g., $\text{Reach}(\top)$).
↪ This characterization **misses** memoryless-determined objectives.

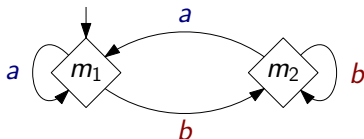
Finite memory

Finite-memory strategy \approx **memory structure** + **next-action function**.

Memory structure

Memory structure $(M, m_{\text{init}}, \alpha_{\text{upd}})$: finite set of states M , initial state m_{init} , update function $\alpha_{\text{upd}}: M \times C \rightarrow M$.

Ex.: remember whether a or b was last seen:



Given an arena $\mathcal{A} = (S, S_1, S_2, E)$: **next-action function** $\alpha_{\text{next}}: S_i \times M \rightarrow E$.

Memoryless strategies use **memory structure** \rightarrow  C .

Finite-memory determinacy

Finite-memory determinacy

An objective W is **finite-memory-determined** if **there exists a finite memory structure** \mathcal{M} that suffices to play optimally for both players **in all arenas** \mathcal{A} .

Remark

Usually, the definition inverts the order of the quantifiers. The order has an impact in **finite arenas**,¹³ but not in **infinite arenas**.

¹³Bouyer, Le Roux, et al., "Games Where You Can Play Optimally with Arena-Independent Finite Memory", 2020.

Get rid of prefix-independence? Right congruence

Let L be a language of **finite** words on alphabet C .

Myhill-Nerode congruence

For $x, y \in C^*$, $x \sim_L y$ if for all $z \in C^*$, $xz \in L \Leftrightarrow yz \in L$.

Myhill-Nerode theorem¹⁴

L is **regular** if and only if \sim_L has **finitely many equivalence classes**.
The **equivalence classes of \sim_L** correspond to the **states of the minimal DFA for L** .

¹⁴Nerode, "Linear Automaton Transformations", 1958.

Get rid of prefix-independence? Right congruence

Let W be a language of **infinite** words (= an objective) on alphabet C .

Right congruence

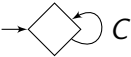
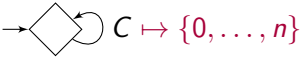
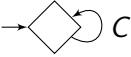
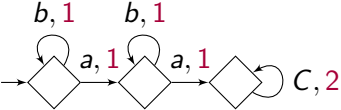
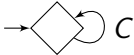
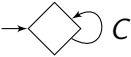
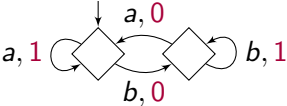
For $x, y \in C^*$, $x \sim_W y$ if for all $z \in C^\omega$, $xz \in W \Leftrightarrow yz \in W$.

Links with ω -regularity?

- If W is **ω -regular**, then \sim_W has finitely many equivalence classes. In this case, there is a DFA \mathcal{M}_\sim “*prefix-classifier*” associated with \sim_W .
- Reciprocal not true.

W is **prefix-independent** if and only if \sim_W has only one equivalence class.

Four examples

Objective	Prefix-classifier \mathcal{M}_{\sim}	Memory
$C = \{0, \dots, n\}$, Parity condition		
$C = \mathbb{Q}$, $W = \text{MP}^{\geq 0}$		No finite structure
$C = \{a, b\}$, $W = b^*ab^*aC^\omega$		
$C = \{a, b\}$, $W = C^*(ab)^\omega$		

Main result

Let $W \subseteq C^\omega$ be an objective.

Theorem

If a finite memory structure \mathcal{M} suffices to play optimally in infinite arenas for both players, **then**

- $(\mathcal{M}_\sim$ is finite), and
- W is recognized by a **parity automaton** $(\mathcal{M}_\sim \otimes \mathcal{M}, p)$.

\rightsquigarrow if $\mathcal{M}_\sim \otimes \mathcal{M} = (M, m_{\text{init}}, \alpha_{\text{upd}})$,

$$p: M \times C \rightarrow \{0, \dots, n\}.$$

Generalizes [CN06]¹⁵ (where $\mathcal{M}_\sim = \mathcal{M} = \rightarrow \diamond \rightarrow C$).

¹⁵Colcombet and Niviński, "On the positional determinacy of edge-labeled games", 2006.

Corollary

Let $W \subseteq C^\omega$ be an objective.

Characterization

W is **finite-memory-determined** if and only if W is ω -**regular**.

Proof. W is finite-memory-determined.

[BRV22] \implies W is recognized by a deterministic parity automaton (ω -regular).
 \implies this parity automaton (as a memory) suffices in infinite arenas.¹⁶

¹⁶Zielonka, "Infinite Games on Finitely Coloured Graphs with Applications to Automata on Infinite Trees", 1998.

Summary

Contributions

- **Strategic characterization** of ω -regularity, generalizing [CN06].¹⁷
- (*Not mentioned*) New **one-to-two-player lift** for zero-sum games on infinite graphs.

Future work

- Other classes of arenas (e.g., finitely branching)?
- Only **one** player has FM optimal strategies?

Thanks!

¹⁷Colcombet and Nawiński, “On the positional determinacy of edge-labeled games”, 2006.